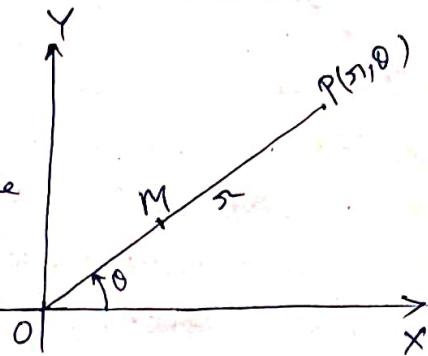


## Two dimensional motion, Velocity and acceleration in Polar co-ordinates

Find the radial and cross radial (or transverse) components of velocity and accel<sup>n</sup> in terms of polar co-ordinates at a particle moving in a plane.

A set of rectangular axes  $XOX'$  and  $YOY'$  are taken in the plane of motion of the particle. Let  $P(r, \theta)$  be the position of the particle at time  $t$ .



Let  $\hat{i}, \hat{j}$  be unit vectors along  $X'$  and  $Y'$  respectively.  $\hat{\alpha}, \hat{\beta}$  be unit vectors along  $OP$  and  $\perp$  to  $OP$  (in the sense of  $\theta$  increasing).

$OM = r$ , is taken on  $OP$ .  $\therefore \vec{OM} = r \hat{\alpha}$ . Co-ordinates of  $M$  are  $(r \cos \theta, r \sin \theta) = (r \hat{i}, r \hat{j})$ .  $\therefore \vec{OM} = \hat{i} r \cos \theta + \hat{j} r \sin \theta$

$$\therefore \hat{\alpha} = \hat{i} \cos \theta + \hat{j} \sin \theta$$

$$\text{Similarly } \hat{\beta} = \hat{i} \sin(\theta + \frac{\pi}{2}) + \hat{j} \cos(\theta + \frac{\pi}{2}) = -\hat{i} \sin \theta + \hat{j} \cos \theta$$

$$\frac{d\hat{\alpha}}{d\theta} = -\hat{i} \sin \theta + \hat{j} \cos \theta = \hat{\beta} \quad \therefore \frac{d\hat{\alpha}}{dt} = \frac{d\hat{\alpha}}{d\theta} \cdot \dot{\theta} = \hat{\beta} \dot{\theta}$$

$$\frac{d\hat{\beta}}{d\theta} = -\hat{i} \cos \theta - \hat{j} \sin \theta = -\hat{\alpha} \quad \therefore \frac{d\hat{\beta}}{dt} = -\hat{\alpha} \dot{\theta}$$

Let  $V_r$  and  $V_\theta$  be the components of vel. along  $OP$  and  $\perp$  to  $OP$ .

$$\begin{aligned} \therefore \vec{V} &= (V_r) \hat{\alpha} + (V_\theta) \hat{\beta} = \frac{d(OP)}{dt} = \frac{d(r\hat{\alpha})}{dt} = \frac{dr}{dt} \hat{\alpha} + r \frac{d\hat{\alpha}}{dt} \\ &= \frac{dr}{dt} \hat{\alpha} + r \frac{d\hat{\alpha}}{d\theta} \cdot \frac{d\theta}{dt} = \frac{dr}{dt} \hat{\alpha} + r \frac{d\theta}{dt} \hat{\beta} \end{aligned}$$

$$\begin{aligned} \therefore V_r &= \frac{dr}{dt} \text{ or } \dot{r} \\ V_\theta &= r \frac{d\theta}{dt} \text{ or } r\dot{\theta} \end{aligned}$$

Let  $f_r$  and  $f_\theta$  be radial and cross radial comp<sup>s</sup> of accel<sup>n</sup>

$$\therefore \vec{f} = f_r \hat{\alpha} + f_\theta \hat{\beta} = \frac{d(\vec{V})}{dt} = \frac{d}{dt} (\dot{r} \hat{\alpha} + r \dot{\theta} \hat{\beta})$$

$$= \dot{r} \hat{\alpha} + \dot{r} \hat{\alpha} + \dot{r} \dot{\theta} \hat{\beta} + r \ddot{\theta} \hat{\beta} + r \dot{\theta} \dot{\hat{\beta}}$$

$$= \dot{r} \hat{\alpha} + r \dot{\theta} \hat{\beta} + \dot{r} \dot{\theta} \hat{\beta} + r \ddot{\theta} \hat{\beta} - r \dot{\theta} \hat{\alpha}$$

$$= (\dot{r} - r \dot{\theta}^2) \hat{\alpha} + (2\dot{r} \dot{\theta} + r \ddot{\theta}) \hat{\beta}$$

$$\therefore f_r = \dot{r} - r \dot{\theta}^2, \quad f_\theta = 2\dot{r} \dot{\theta} + r \ddot{\theta} = \frac{1}{r} \frac{d(r^2 \dot{\theta})}{dt}$$

$$\begin{aligned} \therefore f_r &= \dot{r} - r \dot{\theta}^2 \\ f_\theta &= \frac{1}{r} \frac{d(r^2 \dot{\theta})}{dt} \end{aligned}$$

Ex-1 A particle describes the curve  $r = ae^{\theta}$  in such a manner that its accel<sup>n</sup> has no radial comp. Show that its angular vel. is const and that the magnitudes of vel. and accel<sup>n</sup> at a point are each proportional to radius vector  $r$ .

Ans Radial accel<sup>n</sup> at  $(r, \theta)$  at <sup>any</sup> time  $t = 0$ . (given)

$$\therefore \ddot{r} - r(\dot{\theta})^2 = 0 \quad \dots (1)$$

$$r = ae^{\theta}, \quad \dot{r} = ae^{\theta} \cdot \dot{\theta} = r\dot{\theta}$$

$$\ddot{r} = \dot{r}\dot{\theta} + r\ddot{\theta} = r\dot{\theta}^2 + r\ddot{\theta}$$

$$\text{From (1)} \quad r\dot{\theta}^2 + r\ddot{\theta} - r\dot{\theta}^2 = 0 \quad \text{or, } r\ddot{\theta} = 0 \quad \text{or, } \ddot{\theta} = 0$$

$$\therefore \dot{\theta} = \text{const} = \omega \text{ (say) (proved)}$$

$$\text{Radial velocity } v_r = \dot{r} = r\dot{\theta} = r\omega$$

$$\text{Cross-radial vel. } v_{\theta} = r\dot{\theta} = r\omega$$

$$\therefore \text{Mag. of vel.} = \sqrt{v_r^2 + v_{\theta}^2} = \sqrt{r^2\omega^2 + r^2\omega^2} = \sqrt{2} r\omega$$

$$\therefore \text{magnitude of velocity is } \propto r \text{ (proved)}$$

$$\text{Cross-radial accel<sup>n</sup> } f_{\theta} = \frac{1}{r} \frac{d}{dt}(r^2\dot{\theta}) = \frac{1}{r} \frac{d}{dt}(r^2\omega) = \frac{\omega}{r} \cdot 2r\dot{r}$$

$$= 2\omega^2 r \quad [\because \dot{r} = r\omega]$$

$$\text{We have } f_r = 0 \text{ (given)}$$

$$\text{Magnitude of accel<sup>n</sup>} = \sqrt{f_r^2 + f_{\theta}^2} = \sqrt{4\omega^4 r^2} = 2\omega^2 r, \\ \text{which is proportional to } r.$$

Ex-2 If the path of a particle is the curve  $r = ae^{\cot\alpha \theta}$  and if the radius vector ~~to~~ <sup>of</sup> the particle has a const angular vel, show that the resultant accel<sup>n</sup> of the particle makes an angle  $\alpha$  with the radius vector and is of magnitude  $\frac{v^2}{r}$ ,  $v$  is the speed of the particle.

Ans Let  $P(r, \theta)$  be the position of the particle at time  $t$ .

Angular velocity about the pole  $= \dot{\theta} = \text{const} = \omega$  (say)

$$r = ae^{\cot\alpha \theta}, \quad \therefore \dot{r} = a(\cot\alpha) e^{\cot\alpha \theta} \cdot \dot{\theta} = (\cot\alpha) r\omega$$

$$\ddot{r} = (\cot\alpha)\omega \cdot \dot{r} = (\cot^2\alpha) \omega^2 r$$

$$\text{Radial velocity } v_r = \dot{r} = \cot\alpha \cdot r\omega$$

$$\text{Cross-radial velocity } v_{\theta} = r\dot{\theta} = r\omega$$

$$\therefore v^2 = v_r^2 + v_{\theta}^2 = r^2\omega^2 \cot^2\alpha + r^2\omega^2 = r^2\omega^2(1 + \cot^2\alpha) = r^2\omega^2 \csc^2\alpha$$

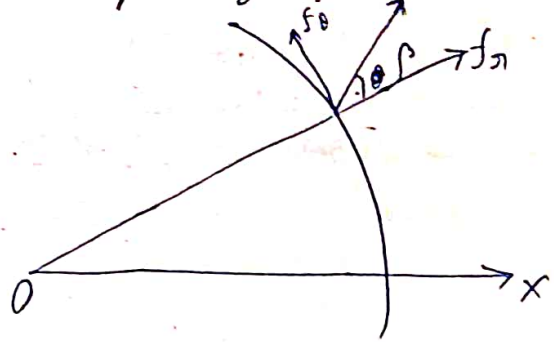
$$\text{Radial accel<sup>n</sup> } f_r = \ddot{r} - r\dot{\theta}^2 = (\cot^2\alpha)\omega^2 r - r\omega^2 = \omega^2 r(\cot^2\alpha - 1)$$

$$\text{Cross-radial accel<sup>n</sup> } f_{\theta} = \frac{1}{r} \frac{d}{dt}(r^2\dot{\theta}) = \frac{1}{r} \frac{d}{dt}(r^2\omega) = \frac{\omega}{r} \cdot 2r\dot{r} = 2\omega^2 \cot\alpha \cdot r$$

$$\begin{aligned} \text{Resultant accel}^n &= \sqrt{f_{\dot{r}}^2 + f_{\dot{\theta}}^2} = \sqrt{w^4 r^2 (\cot^2 \alpha - 1)^2 + 4w^4 r^2 \cot^2 \alpha} \\ &= w^2 r \sqrt{(\cot^2 \alpha - 1)^2 + 4\cot^2 \alpha} = w^2 r \sqrt{(\cot^2 \alpha + 1)^2} = w^2 r (\cot^2 \alpha + 1) \\ &= w^2 r \operatorname{cosec}^2 \alpha = \frac{w^2 r^2 \operatorname{cosec}^2 \alpha}{r} = \frac{v^2}{r} \end{aligned}$$

Let the resultant acceleration make an angle  $\beta$  with the radius vector.

$$\begin{aligned} \therefore \tan \beta &= \frac{f_{\dot{\theta}}}{f_{\dot{r}}} = \frac{2w^2 r \cot \alpha}{r w^2 (\cot^2 \alpha - 1)} \\ &= \frac{2 \cot \alpha}{\cot^2 \alpha - 1} = \frac{2 \tan \alpha}{1 - \tan^2 \alpha} = \tan 2\alpha \\ \therefore \beta &= 2\alpha \quad (\text{proved}) \end{aligned}$$



Ex-3 A point moves on a plane with constant linear velocity  $wa$  and its angular velocity about the pole is  $\frac{w}{a}$ . Show that its accel<sup>n</sup> is equal to  $3w^2 r$ .

Let  $P(r, \theta)$  be the position of the particle at time  $t$ .

$$\text{Radial vel. } v_r = \dot{r}, \quad \text{Cross radial vel. } = v_{\theta} = r\dot{\theta} = r \cdot \frac{w}{a} = \frac{wr}{a}$$

$$\text{Linear Velocity} = \sqrt{v_r^2 + v_{\theta}^2} = \sqrt{\dot{r}^2 + \frac{w^2 r^2}{a^2}} = wa \quad (\text{given})$$

$$\therefore \dot{r}^2 + \frac{w^2 r^2}{a^2} = w^2 a^2 \quad \text{or} \quad \dot{r}^2 = w^2 a^2 - \frac{w^2 r^2}{a^2} = w^2 \left( \frac{a^4 - r^2}{a^2} \right)$$

$$\therefore \dot{r} = \pm \frac{w \sqrt{a^4 - r^2}}{a}$$

$$\ddot{r} = \pm \frac{w}{a} \cdot \frac{1}{2} (\sqrt{a^4 - r^2})^{-1} (-4r^3 \dot{r}) = \mp \frac{2r^3 w}{a} \dot{r} \frac{1}{\sqrt{a^4 - r^2}}$$

$$= \mp \frac{2r^3 w}{a \sqrt{a^4 - r^2}} \cdot \left( \pm \frac{w \sqrt{a^4 - r^2}}{a} \right) = - \frac{2w^2 r^3}{a^2}$$

$$\text{Radial accel}^n f_r = \dot{r} - r\dot{\theta}^2 = - \frac{2w^2 r^3}{a^2} - r \cdot \frac{w^2 r^2}{a^2} = - \frac{3w^2 r^3}{a^2}$$

$$\text{Cross radial accel}^n f_{\theta} = \frac{1}{r} \frac{d}{dt} (r^2 \dot{\theta}) = \frac{1}{r} \frac{d}{dt} \left( r^2 \cdot \frac{w}{a} \right) = \frac{w}{a} \cdot \frac{1}{r} \cdot 2r \dot{r}$$

$$= \frac{2wr}{a} \left( \pm \frac{w \sqrt{a^4 - r^2}}{a} \right) = \pm \frac{3w^2 r \sqrt{a^4 - r^2}}{a^2}$$

$$\text{Magnitude of accel}^n = \sqrt{f_r^2 + f_{\theta}^2} = \sqrt{\frac{9w^4 r^6}{a^4} + \frac{9w^4 r^2 (a^4 - r^2)}{a^4}}$$

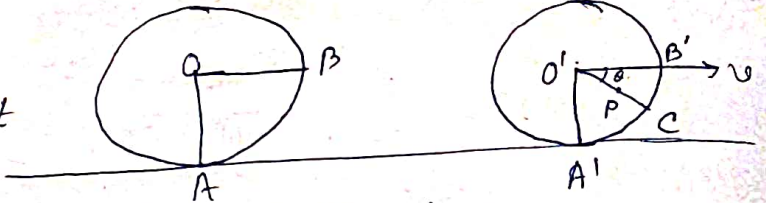
$$= \frac{3w^2 r}{a^2} \sqrt{r^2 + a^4 - r^2}$$

$$= \frac{3w^2 r}{a^2} \cdot a^2 = 3w^2 r \quad (\text{proved})$$

Ex-4

Q3 An insect crawls at a const. rate  $u$  along the spoke of a cart wheel of radius  $a$ . The cart moving with a const vel.  $v$  by pure rolling. Find the accel<sup>n</sup> of the insect along and perp. to the spoke.

Let  $O$  be the centre of the wheel and  $A$  be the pt of contact initially. Let  $O'$  be the position of the centre and  $A'$  be the pt of contact at time  $t$ .



Let  $P$  be the position of the insect on the spoke  $O'C$  making an angle  $\theta$  with the horizontal direction  $O'B'$ . Let  $O'P = r$ ,  $\angle B'O'C = \theta$ .

$\therefore$  the insect crawls along the spoke with const vel.  $u$ ,

$$\therefore \frac{dr}{dt} = u.$$

$\therefore$  the wheel rolls, the vel. of the pt. of contact = 0.

$$\therefore v - a\dot{\theta} = 0 \quad \therefore \dot{\theta} = \frac{v}{a}.$$

$$\begin{aligned} \text{Accel}^n \text{ of the insect along the spoke} &= \ddot{r} - r\dot{\theta}^2 = 0 - r \frac{v^2}{a^2} \left[ \begin{array}{l} \because \dot{r} = u \\ \therefore \ddot{r} = 0 \end{array} \right] \\ &= - \frac{v^2 r}{a^2}. \end{aligned}$$

$$\begin{aligned} \text{Accel}^n \text{ of the insect } \perp^n \text{ to the spoke} &= \frac{1}{r} \frac{d(r\dot{\theta})}{dt} = \frac{1}{r} \cdot \frac{d}{dt} \left( r \cdot \frac{v}{a} \right) \\ &= \frac{v}{a} \cdot \frac{1}{r} \cdot 2r\dot{r} = \frac{2v}{a} \cdot u. \end{aligned}$$

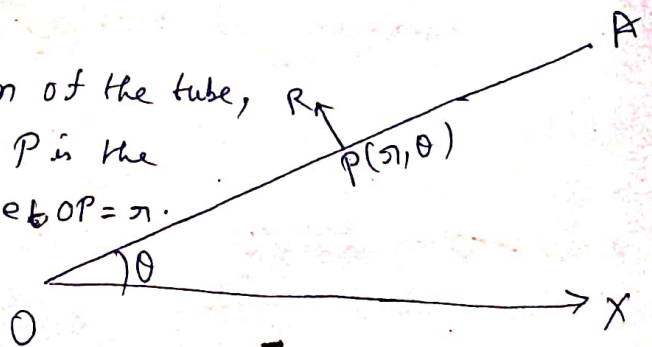
Ex-5 A st smooth tube revolves with angular vel.  $\omega$  in a horizontal plane about one extremity which is fixed. At zero time the particle starts with no initial vel. from a pt inside the tube at distance  $a$  from the fixed end, find the distance of the particle and the normal pressure of the tube at time  $t$ .

If the length of the tube be  $b$ , show that the direction in which the particle flies out is inclined to the tube at an angle

$$\tan^{-1} \frac{b}{\sqrt{b^2 - a^2}}$$

Let  $OX$  be the initial position of the tube, and  $OA$  be the position at time  $t$ .  $P$  is the position of the particle at that time,  $OP = r$ .

$\angle POX = \theta$ ,  $R =$  horizontal normal pressure of the tube.



$m =$  mass of the particle.

The equations of motion along and  $\perp$  to OP are,

$$m(\ddot{x} - \omega^2 x) = 0 \quad \dots (1)$$

$$m \left\{ \frac{1}{\omega} \frac{d}{dt} (\dot{x}^2 \omega) \right\} = R \quad \dots (2)$$

from (1)  $\ddot{x} - \omega^2 x = 0$ ,  $\therefore \omega$ ,  $\ddot{x} - \omega^2 x = 0$ .

Let  $x = e^{\lambda t}$  be a sol<sup>n</sup> of the equation.

$\therefore$  auxiliary equation is  $\lambda^2 - \omega^2 = 0 \quad \therefore \lambda = \pm \omega$

$\therefore$  The general sol<sup>n</sup> is  $x = C_1 \cosh \omega t + C_2 \sinh \omega t$

$\therefore \dot{x} = C_1 \omega \sinh \omega t + C_2 \omega \cosh \omega t$

When  $t=0$ ,  $x=a$ ,  $\therefore a = C_1 \cdot 1 + C_2 \cdot 0 \quad \therefore C_1 = a$

When  $t=0$ ,  $\dot{x} = 0 \quad \therefore 0 = 0 + C_2 \omega \cdot 1 \quad \therefore C_2 = 0$ .

$\therefore x = a \cosh \omega t$ .

This gives the ~~normal pressure~~ distance of the particle at time

$t$ . We have,  $\dot{x} = a\omega \sinh \omega t$

from (2)  $R = \frac{m}{\omega} \cdot \frac{d}{dt} (\dot{x}^2 \omega) = \frac{m}{\omega} \cdot \omega \cdot 2\dot{x}\ddot{x}$   
 $= 2m\omega a\omega \sinh \omega t = 2m\omega^2 a \sinh \omega t$

This gives the normal pressure at time  $t$ .

Let the particle reaches the end of the tube at time  $t_1$ , then

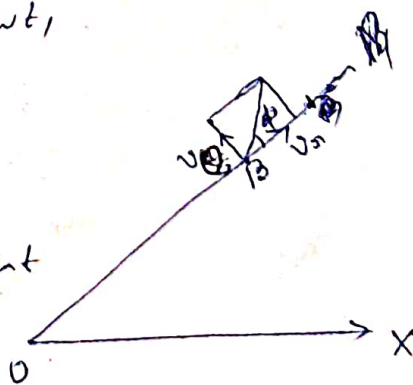
$x = b$ .

$\therefore b = a \cosh \omega t_1, \quad \therefore \cosh \omega t_1 = \frac{b}{a}, \quad \therefore \sinh \omega t_1 = \sqrt{\frac{b^2}{a^2} - 1}$   
 $= \frac{1}{a} \sqrt{b^2 - a^2}$

At  $t = t_1$ ,  $V_x = [\dot{x}]_{t=t_1} = a\omega \sinh \omega t_1$

$V_y = [\dot{y}]_{t=t_1} = b\omega$

At the end the particle flies out in the direction of the resultant vel. Let the resultant vel. makes an angle  $\phi$  with the tube.



$\therefore \tan \phi = \frac{V_y}{V_x} = \frac{b\omega}{a\omega \sinh \omega t_1} = \frac{b}{a \frac{1}{a} \sqrt{b^2 - a^2}} = \frac{b}{\sqrt{b^2 - a^2}}$

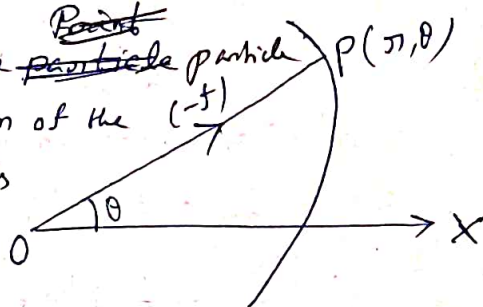
$\therefore \phi = \tan^{-1} \frac{b}{\sqrt{b^2 - a^2}}$ .

Ex-6

A ~~particle~~ particle starts from the origin in the direction of the initial line with vel:  $\frac{f}{\omega}$  and moves with constant angular vel.  $\omega$  about the origin and with constant negative radial accel<sup>n</sup> ( $-f$ ). Prove that the eqn of the path is  $\omega^2 r = f(1 - e^{-\theta})$ .

Also show that the rate of growth of radial vel. is never +ve and tends to zero.

Let  $P(r, \theta)$  be the position of the ~~particle~~ particle at time  $t$ . The equation of motion of the ~~particle~~ particle in the radial direction is



$$\ddot{r} - r\dot{\theta}^2 = -f$$

$$\text{or, } \ddot{r} - r\omega^2 = -f \quad \dots (1)$$

for C.F. we solve,  $\ddot{r} - r\omega^2 = 0 \quad \dots (2)$

Let  $r = e^{\lambda t}$  be a sol<sup>n</sup> of (2)

$\therefore$  The auxiliary equation is  $\lambda^2 - \omega^2 = 0, \therefore \lambda = \pm \omega$ .

$$\therefore \text{C.F.} = C_1 e^{\omega t} + C_2 e^{-\omega t}$$

Equation (1) can be written as,  $(D^2 - \omega^2)r = -f$  [ $D \equiv \frac{d}{dt}$ ]

$$\therefore \text{P.I.} = \frac{1}{D^2 - \omega^2} (-f) = \frac{f}{\omega^2 (1 - \frac{D^2}{\omega^2})}$$

$$= \frac{f}{\omega^2} \left[ 1 + \frac{D^2}{\omega^2} + \dots \right] = \frac{f}{\omega^2}$$

$$\therefore \text{G.S. of (1) is } r = C_1 e^{\omega t} + C_2 e^{-\omega t} + \frac{f}{\omega^2}$$

$$\dot{r} = C_1 \omega e^{\omega t} - C_2 \omega e^{-\omega t}$$

at  $t=0, r=0$

$$\therefore 0 = C_1 + C_2 + \frac{f}{\omega^2} \quad \dots (3)$$

at  $t=0, \dot{r} = \frac{f}{\omega}$

$$\therefore \frac{f}{\omega} = C_1 \omega - C_2 \omega$$

$$\therefore \frac{f}{\omega^2} = C_1 - C_2 \quad \dots (4)$$

(3) + (4) gives,  $\frac{f}{\omega^2} = 2C_1 + \frac{f}{\omega^2} \quad \therefore C_1 = 0$ .

From (3)  $\therefore C_2 = -\frac{f}{\omega^2}$

$$\therefore r = -\frac{f}{\omega^2} e^{-\omega t} + \frac{f}{\omega^2}$$

$$\text{or, } r = \frac{f}{\omega^2} (1 - e^{-\omega t}) \quad \dots (5)$$

We have  $\dot{\theta} = \omega$  or  $\frac{d\theta}{dt} = \omega, \therefore d\theta = \omega dt$

Integrating,  $\theta = \omega t + c$

when  $t=0, \theta=0, \therefore c=0$ .

$$\therefore \theta = \omega t$$

$\therefore (5)$  becomes  $r = \frac{f}{\omega^2} (1 - e^{-\omega t})$  or,  $\omega^2 r = f(1 - e^{-\omega t})$

This is the equation of the path of the ~~particle~~ particle

Radial vel =  $\dot{r} = \frac{f}{\omega} e^{-\omega t}$   
 rate of growth of radial vel. =  $\frac{d}{dt}(\dot{r}) = \frac{d}{dt}\left(\frac{f}{\omega} e^{-\omega t}\right) = -f e^{-\omega t}$ ,

which is not +ve.

When  $t \rightarrow \infty$ ,  $e^{-\omega t} = \frac{1}{e^{\omega t}} \rightarrow 0$ .

$\therefore$  rate of growth of radial velocity tends to zero (proved)

Ex-7 If the angular vel. about the origin be a const  $\omega$ , deduce ~~that~~

the cross radial component of the rate of change of accel<sup>n</sup> of the particle and show that if this rate of change of accel<sup>n</sup> be zero, then

$$\frac{d^2 r}{dt^2} = \frac{1}{3} \omega^2 r.$$

Ans:- Let  $P(r, \theta)$  be the position of the particle at time  $t$ . Let  $\hat{\alpha}$  and  $\hat{\beta}$  be the unit vectors along  $OP$  and  $\perp$  to  $OP$ .

If  $f_r$  and  $f_\theta$  be the radial and cross radial components of acceleration, then  ~~$f_r = \dot{r} - r\dot{\theta}^2$~~

Then  $f_r = \dot{r} - r\dot{\theta}^2 = \dot{r} - r\omega^2$

$$f_\theta = \frac{1}{r} \frac{d}{dt}(r^2 \dot{\theta}) = \frac{\omega}{r} \cdot 2r\dot{r} = 2\omega \dot{r}$$

Accel<sup>n</sup> vector =  $\vec{f} = f_r \hat{\alpha} + f_\theta \hat{\beta}$

$$\therefore \frac{d}{dt}(\vec{f}) = \frac{d}{dt}(f_r \hat{\alpha} + f_\theta \hat{\beta}) = \frac{d}{dt}(f_r) \hat{\alpha} + f_r \frac{d}{dt} \hat{\alpha} + \frac{d}{dt}(f_\theta) \hat{\beta} + f_\theta \frac{d}{dt} \hat{\beta}$$

If  $\hat{i}, \hat{j}$  be the unit vectors along  $Ox$  and  $\perp$  to  $Ox$  respectively, then

$$\hat{\alpha} = \hat{i} \cos \theta + \hat{j} \sin \theta$$

$$\hat{\beta} = \hat{i} \cos(\theta + \frac{\pi}{2}) + \hat{j} \sin(\theta + \frac{\pi}{2}) = -\hat{i} \sin \theta + \hat{j} \cos \theta$$

$$\therefore \frac{d}{dt} \hat{\alpha} = (-\hat{i} \sin \theta + \hat{j} \cos \theta) \dot{\theta} = \hat{\beta} \omega$$

$$\frac{d}{dt} \hat{\beta} = (-\hat{i} \cos \theta - \hat{j} \sin \theta) \dot{\theta} = -\hat{\alpha} \omega$$

$$\therefore \frac{d}{dt} \vec{f} = \frac{d}{dt} f_r \hat{\alpha} + f_r \hat{\beta} \omega + \frac{d}{dt} f_\theta \hat{\beta} - f_\theta \hat{\alpha} \omega$$

$$= \left( \frac{d}{dt} f_r - f_\theta \omega \right) \hat{\alpha} + \left( f_r \omega + \frac{d}{dt} f_\theta \right) \hat{\beta}$$

$\therefore$  Cross radial component of the rate of change of acceleration

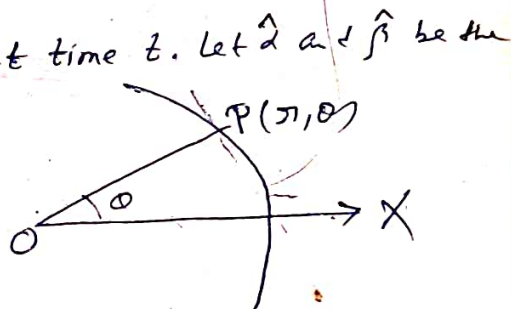
$$= \frac{d}{dt} f_\theta + f_r \omega = \frac{d}{dt} (2\omega \dot{r}) + (\dot{r} - r\omega^2) \omega$$

$$= 2\omega \dot{r} + \dot{r} \omega - r\omega^3 = 3\dot{r} \omega - r\omega^3.$$

If this component be zero, then.

$$3\dot{r} \omega - r\omega^3 = 0$$

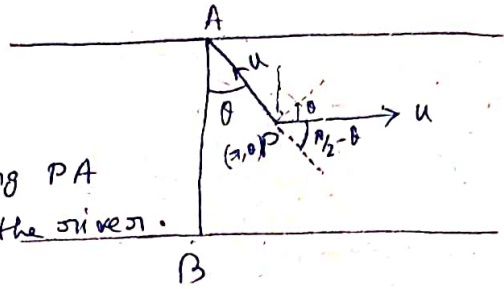
$$\text{or, } \dot{r} = \frac{1}{3} r \omega^2 \text{ (proved)}$$



Ex-8

A and B are points on opposite bank of a river of width  $a$  and AB is at right angled to the direction of the flow of river. A boat leaves B and is rowed with constant speed  $u$  always directed towards A. If the river flows with the speed  $u$ , find the path of the boat.

Let  $P$  be the position of the boat at time  $t$ , where  $AP = r$ ,  $\angle PAB = \theta$ .



The boat has two velocities,  $u$  along PA and  $u$  along the direction of the flow of the river.

Radial velocity is  $\frac{dr}{dt} = u \cos(\frac{\pi}{2} - \theta) - u = u \sin \theta - u = u(\sin \theta - 1) \dots (i)$

Cross-radial velocity  $\Rightarrow r \frac{d\theta}{dt} = u \sin(\frac{\pi}{2} - \theta) = u \cos \theta \dots (ii)$

(i)  $\div$  (ii) gives,

$$\frac{dr}{r d\theta} = \frac{\sin \theta - 1}{\cos \theta} = \tan \theta - \sec \theta$$

$$\therefore \frac{dr}{r} = (\tan \theta - \sec \theta) d\theta$$

$\therefore \int \frac{dr}{r} = \int (\tan \theta - \sec \theta) d\theta$   
 $\therefore \log r = \log \sec \theta - \log(\sec \theta + \tan \theta) + \log c$

$$\therefore r = \frac{c \sec \theta}{\sec \theta + \tan \theta} = \frac{c}{1 + \sin \theta}$$

$$\text{or } r(1 + \sin \theta) = c$$

At B,  $\theta = 0$ ,  $r = a$ ,  $\therefore c = a$

$\therefore$  The equation of the path is  $r(1 + \sin \theta) = a$ ,

Ex-9

A particle is at rest on a smooth horizontal plane, which commences to turn about a st line lying on itself with constant angular velocity  $\omega$  downwards. If  $a$  be the distance of the particle from the axis of rotation initially, Show that, the particle will leave the plane at time  $t$ , given by the equation,

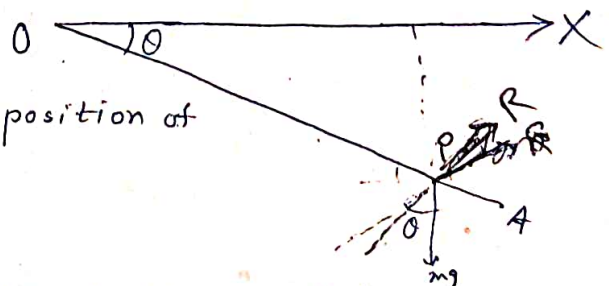
$$a \sinh \omega t + \frac{g}{2\omega^2} \cosh \omega t = \frac{g}{\omega^2} \cos \omega t$$

OX is the initial horizontal position of the plane and OA is the position at time  $t$ . Then P is the position of the particle.  $OP = r$  &  $\angle POX = \theta$ .

$m$  = mass of the particle

$R$  = Normal pressure of the plane on the particle

The equations of motion are,





$$m \left\{ \frac{d^2 \theta}{dt^2} - \omega \left( \frac{d\theta}{dt} \right)^2 \right\} = mg \sin \theta \dots (1)$$

$$m \cdot \frac{1}{\omega} \frac{d(\omega^2 \frac{d\theta}{dt})}{dt} = -R + mg \cos \theta \dots (2)$$

By the condition  $\frac{d\theta}{dt} = \omega$  on  $d\theta = \omega dt \therefore \theta = \omega t + C_1$

When  $t=0, \theta=0, \therefore C_1=0$

$\therefore \theta = \omega t$

From (1)  $\frac{d^2 \theta}{dt^2} - \omega^2 = g \sin \omega t$

C.F. is,  $C_2 \cos \omega t + C_3 \sin \omega t$

P.I. is  $\frac{1}{D^2 - \omega^2} g \sin \omega t = \frac{g \sin \omega t}{-\omega^2 - \omega^2} = -\frac{g \sin \omega t}{2\omega^2}$

The A.S. is

$$\theta = C_2 \cos \omega t + C_3 \sin \omega t - \frac{g}{2\omega^2} \sin \omega t$$

$$\frac{d\theta}{dt} = C_2 \omega \sin \omega t + C_3 \omega \cos \omega t - \frac{g}{2\omega} \omega \cos \omega t$$

at  $t=0, \theta=C_2, \frac{d\theta}{dt}=0$

$\therefore C_2 = C_2$

and  $0 = C_3 \omega - \frac{g}{2\omega} \Rightarrow C_3 = \frac{g}{2\omega^2}$

$\therefore \theta = C_2 \cos \omega t + \frac{g}{2\omega^2} (\sin \omega t - \sin \omega t)$

From (2),  $R = mg \cos \omega t - \frac{m\omega}{2\omega} 2\omega \frac{d\theta}{dt}$

$$= -2m\omega \left[ a \omega \sin \omega t + \frac{g}{2\omega} (\cos \omega t - \cos \omega t) \right] + mg \cos \omega t$$

$\therefore R = m \left[ 2g \cos \omega t - 2a\omega^2 \sin \omega t - g \cos \omega t \right]$

The particle will leave the plane when  $R=0$ ,

$$2g \cos \omega t - 2a\omega^2 \sin \omega t - g \cos \omega t = 0$$

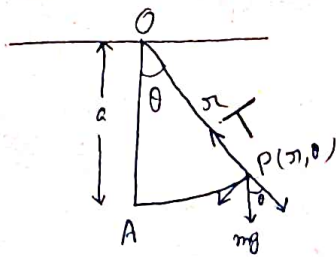
or,  $a \sin \omega t + \frac{g}{2\omega^2} \cos \omega t = \frac{g}{\omega^2} \cos \omega t$  (proved)

Ex-10 A heavy particle hangs from a point O by a string of length a. It is projected horizontally with velocity v such that  $v^2 = (2+5)ag$ .

Show that the string becomes slack when it has described an angle

$$\cos^{-1}\left(-\frac{1}{\sqrt{3}}\right)$$

Let P be any position of the particle. The angle described is  $\theta$ . The particle ~~starts~~ starts from A with a velocity  $v$ , which is given by  $v^2 = (2 + \sqrt{3})ag$ .



The equations of motion are given by,

$$m \left[ \frac{d^2 r}{dt^2} - r \left( \frac{d\theta}{dt} \right)^2 \right] = mg \cos \theta - T \quad (1)$$

$$\text{and } m \left[ \frac{1}{r} \frac{d}{dt} \left( r^2 \frac{d\theta}{dt} \right) \right] = -mg \sin \theta \quad (2)$$

From (2),  $\frac{1}{r} \frac{d}{dt} \left( r^2 \frac{d\theta}{dt} \right) = -g \sin \theta$

Since  $r$  is a constant and equal to  $a$ ,

So,  $\frac{1}{a} \cdot a^2 \frac{d^2 \theta}{dt^2} = -g \sin \theta$  or,  $a \frac{d^2 \theta}{dt^2} = -g \sin \theta$  or,  $\frac{d^2 \theta}{dt^2} = -\frac{g}{a} \sin \theta$

Multiplying both sides by  $2 \frac{d\theta}{dt}$  and integrating we have,

$$\left( \frac{d\theta}{dt} \right)^2 = 2 \frac{g}{a} \cos \theta + C \quad (3)$$

Initially,  $v^2 = a^2 \left( \frac{d\theta}{dt} \right)^2 + a^2 \left( \frac{d\theta}{dt} \right)^2 = (2 + \sqrt{3})ag$

ie  $\left( \frac{d\theta}{dt} \right)^2 = \frac{(2 + \sqrt{3})g}{a}$  [ $\because r$  is a constant =  $a$ ]

So (3) becomes,

$$\frac{(2 + \sqrt{3})g}{a} = \frac{2g}{a} \cdot 1 + C \quad [\because \theta = 0]$$

$$\text{ie } C = \frac{2g}{a} - \frac{2g}{a} + \frac{\sqrt{3}g}{a} = \frac{\sqrt{3}g}{a}$$

So (3) becomes,  $\left( \frac{d\theta}{dt} \right)^2 = \frac{2g}{a} \cos \theta + \frac{\sqrt{3}g}{a} \quad (4)$

From (1)  $-m r \left( \frac{d\theta}{dt} \right)^2 = mg \cos \theta - T$

ie.  $\left( \frac{d\theta}{dt} \right)^2 = \frac{T}{ma} - \frac{mg \cos \theta}{ma} \quad [\because r = a] \quad (5)$

From (4) and (5) we have,

$$\frac{2g \cos \theta}{a} + \frac{\sqrt{3}g}{a} = -\frac{mg \cos \theta}{a} \quad [\because \text{When the string will slack then, } T = 0]$$

ie  $2 \cos \theta = -\cos \theta - \sqrt{3}$

or  $3 \cos \theta = -\sqrt{3}$  ie  $\cos \theta = -\frac{\sqrt{3}}{3} = -\frac{1}{\sqrt{3}}$

ie  $\theta = \cos^{-1} \left( -\frac{1}{\sqrt{3}} \right)$